

Topological analysis of public transport networks' recoverability

NAS group seminar

Renzo Massobrio

Apr 29, 2022, Delft, NL



Margarita-Salas call for postdoctoral research abroad by Universidad de Cádiz (funded by NextGenerationEU).

2 years @ TU Delft + 1 year @ Universidad de Cantabria.

Joined the Smart Public Transport Lab (T&P department @ CiTG) on Feb 2022, supervised by Oded Cats.

Motivation

Reducing the impact of disruptions is key for providing attractive PT services.

Many works assessing vulnerability and robustness of PTN.

Little is known on the topological aspects of the recovery process once disruptions occur.

Motivation

Reducing the impact of disruptions is key for providing attractive PT services.

Many works assessing vulnerability and robustness of PTN.

Little is known on the topological aspects of the recovery process once disruptions occur.

Inspiration

We study the notion of *recoverability*, inspired by the work of Sun et al. (2021) for optical networks.



• G₀(N, L₀) be the L-space representation of a PTN



- G₀(N, L₀) be the L-space representation of a PTN
- M_{G_0} original performance of the network
- We model failure/recovery of *edges* in *K* steps
- Retained performance ratio: $R_{G_i} = \frac{M_{G_i}}{M_{G_0}}$



- G₀(N, L₀) be the L-space representation of a PTN
- *M*_{G0} original performance of the network
- We model failure/recovery of *edges* in *K* steps
- Retained performance ratio: $R_{G_i} = \frac{M_{G_i}}{M_{G_0}}$
- Cumulative performance loss: $S_f = \sum_{i=0}^{i=K} (1 - R_{G_i})$



- G₀(N, L₀) be the L-space representation of a PTN
- *M*_{G0} original performance of the network
- We model failure/recovery of *edges* in *K* steps
- Retained performance ratio: $R_{G_i} = \frac{M_{G_i}}{M_{G_0}}$
- Cumulative performance loss: $S_{f} = \sum_{i=0}^{i=K} (1 - R_{G_{i}})$
- Cumulative performance gain: $S_r = \sum_{i=K+1}^{i=2K} R_{G_i} - R_{G_K}$



- G₀(N, L₀) be the L-space representation of a PTN
- *M*_{G0} original performance of the network
- We model failure/recovery of *edges* in *K* steps
- Retained performance ratio: $R_{G_i} = \frac{M_{G_i}}{M_{G_0}}$
- Cumulative performance loss: $S_f = \sum_{i=0}^{i=K} (1 - R_{G_i})$
- Cumulative performance gain: $S_r = \sum_{i=K+1}^{i=2K} R_{G_i} - R_{G_K}$
- Rebound ratio: $\eta = \frac{S_r}{S_f}$

Performance metrics and failure/recovery strategies

Performance metrics

Connectivity

$$C_G = rac{\sum_{i
eq j \in G} 1_{ ext{exists a path (i,j)}}}{N imes (N-1)}$$

Efficiency

$$E_G = \frac{\sum_{i \neq j \in G} 1/\mathsf{travel_time}(i, j)}{N \times (N - 1)}$$

Performance metrics and failure/recovery strategies

Performance metrics

Connectivity

$$C_{G} = rac{\sum_{i
eq j \in G} 1_{ ext{exists a path (i,j)}}}{N imes (N-1)}$$

Efficiency

$$E_G = rac{\sum_{i
eq j \in G} 1/ ext{travel_time}(i,j)}{N imes (N-1)}$$

Failure/recovery strategies

- *Random*: links are iteratively removed/added to the graph randomly and uniformly.
- *Greedy* (*C_G*): selects the link to remove/add that would render the largest decrease/increase in *C_G*.
- Greedy (E_G) : same but with the E_G performance metric.

Preliminary results

Studied scenarios



(a) Berlin (172 nodes, 183 links)
 (b) Paris (302 nodes, 359 links)
 Figure: Metro networks used in the experiments

Experiments

We simulated a random failure process of K = 30 steps on each city and report the average results for 10 independent executions.

Preliminary results



city	metric	recovery strategy		
		random	greedy C_G	greedy E_G
Berlin	C_{G}	0.833 (12.748;10.619)	1.141 (12.748;14.545)	1.060 (12.748;13.500)
	E_G	0.904 (9.897;8.943)	1.098 (9.897;10.869)	1.102(9.897;10.910)
Paris	CG	0.725 (3.121;2.263)	1.591 (3.121;4.968)	1.321 (3.121;4.122)
	E_G	0.938 (3.474;3.260)	1.240 (3.474;4.307)	1.293 (3.474;4.491)

Table: Average rebound ratio (η), performance loss (S_f), and gain (S_r) with random failure and varying recovery strategies. Notation: η (S_f ; S_r).

Preliminary results

 C_G

 E_G

Paris



Table: Average rebound ratio (η) , performance loss (S_f) , and gain (S_r) with random failure and varying recovery strategies. Notation: η $(S_f; S_r)$.

1.591 (3.121;4.968)

1.240 (3.474;4.307)

1.321 (3.121;4.122)

1.293 (3.474;4.491)

0.725 (3.121;2.263)

0.938 (3.474;3.260)

Outlook

Conclsuions

We are starting research on a topological approach to measure recoverability in PTNs inspired by previous works in the field of optical networks.

Preliminary results showed that greedy recovery heuristics are able to rebound quickly from the loss of performance during the failure process.

Submitted an extended abstract to CASPT 2022.

Outlook

Conclsuions

We are starting research on a topological approach to measure recoverability in PTNs inspired by previous works in the field of optical networks.

Preliminary results showed that greedy recovery heuristics are able to rebound quickly from the loss of performance during the failure process.

Submitted an extended abstract to CASPT 2022.

On-going and future work

- devise other failure and recoverability strategies
- incorporate new performance metrics
- test on a large number of PTNs worldwide
- incorporate equity in the recovery strategy

Thanks for your time :)

Renzo Massobrio

R.M.Massobrio@tudelft.nl